

Photon density at I<sub>detector</sub> due to Source obliquity

Assumption:

No resolution loss yet due to source. Each ray independent of neighbors

For Parallel Rays:  $I_d(x,y) = I_0 e^{-\int \mu(x,y,z) dz}$ 

Limitations

- 1)Finite Source produces rays that aren't parallel Rays originate from a point source
- 2) Finite Detector
- 3) Distortion due to point source geometry
- 4) Resolution loss due to finite source size (not a point)



$$I_{d}(x_{d},y_{d}) = I_{i}(x_{d},y_{d}) \exp[-\int \mu_{0}(x,y,z) dr$$

Photon density at I<sub>detector</sub>

First, what if no object?



Unit area on sphere is smaller than area it subtends on detector. So for unit area on detector, area on sphere reduces by  $\cos(\theta)$ .

**Detector Plane** 

For small solid angles  $\Omega \approx \text{area/distance}^2 = a (\cos \theta)/r^2$  $\frac{\Omega}{4\pi}$  is fraction of radiation from the source covering a full sphere subtends  $4\pi$  steradians, intercepted by Detector

$$I_d = KN \frac{\frac{\Omega}{4\pi}}{a}$$

N photons emitted by source K energy per photon Divide by area a to normalize to detector area

Normalize to  $I_d(0,0) = I_0$ 

$$I_0 = \frac{KN}{4\pi d^2}$$

Now rewriting  $I_i$  in terms of  $I_0$  gives,

$$I_d = I_o \frac{d^2}{r^2} \cos(\theta)$$



$$I_d = I_o e^{-\tau(\frac{x_d}{M}, \frac{y_d}{M})}$$

But 
$$\frac{d}{r} = \cos(\theta)$$

So,

$$I_d = I_o \cos^3(\theta)$$

### Source Intensity on Detector Coordinates

$$I_{0} = \frac{KN}{4\pi d^{2}}$$

$$I_{d} = I_{0} \cos^{3} \theta$$

$$\cos(\theta) = \frac{d}{\sqrt{d^{2} + r_{d}^{2}}} = \frac{1}{\sqrt{1 + \frac{r_{d}^{2}}{d^{2}}}}$$

$$Cos(\theta) = I_{0} \frac{1}{(1 + \frac{r_{d}^{2}}{d^{2}})^{3/2}}$$

$$\cos(\theta) - Obliquity$$

$$\cos^{2} \theta - Inverse Square$$

$$Law$$

# Practical Example

• For a 40 cm FOV with x-ray source 1 m away, how much amplitude modulation will we have due to source obliquity?

$$I_d = I_0 \frac{1}{(1 + \frac{r_d^2}{d^2})^{3/2}}$$

## Depth Dependent Magnification Depth Dependent Magnification

### Photon density change due to object obliquity





An incremental path of the x-ray, dr, can be described by its x, y, and z components.  $\sqrt{1 + 2 + 1 + 2}$ 

$$dr = \sqrt{dx^2 + dy^2 + dz^2}$$

 $\frac{y_d}{y} = \frac{d}{z} \qquad \qquad \frac{x_d}{x} = \frac{d}{z}$ 

Each point in the body (x,y) can be defined in terms of the detector coordinates it will be imaged at.

$$x = \frac{x_d}{d}z \qquad y = \frac{y_d}{d}z$$

Let's make intensity expression parametric in z.

$$dr = dz\sqrt{1 + (dx/dz)^{2} + (dy/dz)^{2}} \qquad dr = dz\sqrt{1 + (x_{d}/d)^{2} + (y_{d}/d)^{2}}$$
$$r_{d} = \sqrt{x_{d}^{2} + y_{d}^{2}} \qquad \longrightarrow \qquad dr = dz\sqrt{1 + r_{d}^{2}/d^{2}}$$

Then, rewriting an earlier description in terms of the detector plane. z/d describes minification to get from detector plane to object.

$$I_{d}(x_{d}, y_{d}) = I_{i} \exp \left[ -\sqrt{1 + \frac{r_{d}^{2}}{d^{2}}} \int \mu_{o} \left( (x_{d}/d)z, (y_{d}/d)z, z \right) dz \right]$$

Putting it all together gives,

$$I_{d} = I_{o} / (((1 + r_{d}^{2})/d^{2})^{3/2}) \exp \left[-\sqrt{1 + \frac{r_{d}^{2}}{d^{2}}} \int \mu_{o} \left((x_{d}/d)z, (y_{d}/d)z, z\right) dz\right]$$

source obliquity

object obliquity



Object  $\mu$  (x,y,z) =  $\mu_0$  rect ((z -  $z_0$ )/L) Object is not a function of x or y, just z.

$$I_d(x_d, y_d) = I_i \exp[-\sqrt{1 + \frac{r_d^2}{d^2}} \mu_o L]$$

If we assume detector is entirely in the near axis,  $r_d^2 \ll d^2$ Then, simplification results,

$$I_d = I_o \ e^{-\mu_0 L}$$



x out of plane Infinite in x

- For  $\mu_0(x,y,z) = \mu_0 \Pi(y/L) \Pi((z z_0)/w)$ Find the intensity on the detector plane Three cases:
  - 1. Blue Line: X-Ray goes through entire object
  - 2. Red Line: X-ray misses object completely
  - 3. Orange Line: X-ray partially goes through object

$$I_{d}(x_{d},y_{d}) = I_{i} \exp \left[ - \sqrt{1 + \frac{r_{d}^{2}}{d^{2}}} \int \mu_{o} \left( (x_{d}/d)z, (y_{d}/d)z, z \right) dz \right]$$



For the blue line, we don't have to worry that the path length through the object will increase as  $r_d$  increases. That is taken care of by the obliquity term  $\sqrt{1+\frac{r_d^2}{d^2}}$ 

For the red path,  $I_d(x_d, y_d) = I_i$ For the orange path, the obliquity term will still help describe the lengthened path. But we need to know the limits in z to integrate

 $\mu_{o}(x,y,z) = \mu_{o} \prod (y/L) \prod ((z - z_{0})/w)$ 



If we think of thin planes along z, each plane will form a rect in y<sub>d</sub> of width dL/z. Instead of seeing this as a Π in y, let's mathematically consider it as a Π in z that varies in width according to the detector coordinate y<sub>d</sub>. Then we have integration only in the variable z. The Π define limits of integration

$$I_d(x_d, y_d) = I_i \exp\left[-\sqrt{1 + \frac{I_d}{d^2}}\mu_0 \int \Pi(\frac{z}{dL}) \Pi(\frac{z-z_0}{w})dz\right]$$

 $y_d$ 



1) X-ray misses object completely

As  $\boldsymbol{y}_d$  grows,first  $\Pi$  contracts and no overlap exists between the  $\Pi$  ,

functions. No overlap case when

 $dL/2y_d < z_0 - w/2$  $|y_d| > dL/(2 z_o - w)$ 

 $I_d = I_i$ 



#### 1) <u>X-ray goes completely through object</u>

As  $y_d \rightarrow 0$ , x-ray goes completely through object This is true for  $dL/2y_d > z_0 + w/2$ 

$$|y_{d}| < dL/(2 z_{o} + w)$$
  
 $I_{d} = I_{i} \exp \{-\mu_{o} \sqrt{1 + \frac{r_{d}^{2}}{d^{2}}} w\}$ 





The above diagram ignores effects of source obliquity and the factor  $\sqrt{1+\frac{d^2}{d^2}}$  in the exponential How would curve look differently if we accounted for both of these?

# Thin section Analysis

See object as an array of planes

 $\mu (\mathbf{x}, \mathbf{y}, \mathbf{z}) = \tau (\mathbf{x}, \mathbf{y}) \,\delta (\mathbf{z} - \mathbf{z}_0)$ 

Analysis simplifies since only one z plane

$$I_{d} = I_{i}e^{(-\sqrt{1+\frac{r_{d}^{2}}{d^{2}}}\tau(\frac{x_{d}}{M},\frac{y_{d}}{M}))}$$

where  $M = d/z_0$  represents object magnification

If we ignore obliquity,  $I_d = I_o e^{(-\tau(\frac{x_d}{M}, \frac{y_d}{M}))}$ 

Or in terms of the notation for transmission, t,

$$I_d = I_o t(\frac{x_d}{M}, \frac{y_d}{M})$$

Note: No resolution loss yet. Point remains a point.